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# Assignment 08

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- Zhankun Luo:(1)Write the functions, implement Quasi-Newton algorithm
- Wen Ou: (2)Give advice on the improvement
- Andres Jara: (3)Give advice on the improvement

```
clear; clc; close all;
x = csvread('input_data.csv'); d = csvread('output_data.csv');
alpha = -0.5; th = 5e-4;
layer = [10, 5];% nodes of hidden layers
act_type = 'sigmoid';
act_out = true; % activatetion on output layer
percent_val = 10; seed = 0; % percent of val.: 10%;
num_trial = 10; batch_size = 2; % batch_size accelerate training speed
[list_error_train_qn, list_error_val_qn, ...
 list_error_train_gd, list_error_val_gd] = deal(zeros(1, num_trial));
for seed = 0:num_trial-1 % seed for rng() -> different train, val
    dataset
        train_method = 'qn';
        [list_error_train_qn(seed+1),list_error_val_qn(seed
+1),~,~,~,~,~]=...
        run_ann(x,d,alpha,th,layer,act_type,act_out,percent_val,...
            seed,train_method,batch_size);
        train_method = 'gd';
        [list_error_train_gd(seed+1),list_error_val_gd(seed
+1),~,~,~,~,~]= ...
        run_ann(x,d,alpha,th,layer,act_type,act_out,percent_val,...
            seed,train_method,batch_size);
end
error_train_qn = mean(list_error_train_qn);
error_val_qn = mean(list_error_val_qn);
error_train_gd = mean(list_error_train_gd);
error_val_gd = mean(list_error_val_gd);
csvwrite('error_train_qn', error_train_qn);
csvwrite('error_val_qn', error_val_qn);
csvwrite('error_train_gd', error_train_gd);
csvwrite('error_val_gd', error_val_gd);
fprintf('error train QN: %.6f%%', 100*error_train_qn);
fprintf('error val QN: %.6f%%', 100*error_val_qn);
fprintf('error train GD: %.6f%%', 100*error_train_gd);
fprintf('error val GD: %.6f%%', 100*error_val_gd);
```

Trial No.: 1 Train method: qn

First 5 val. samples of d & y

d1	d2
0.16	3.7e-13
0.47	7e-14
0.34	5.5e-14
0.34	5.4e-13
0.51	2e-13

y1	y2
0.16	3.7e-13
0.46	1.1e-13
0.35	8.8e-14
0.35	4.9e-13
0.5	2.1e-13

After 2424 epochs

train percent: 90%, MSE: 0.0058%

val percent: 10%, MSE: 0.0038%

Trial No.: 1 Train method: gd

First 5 val. samples of d & y

d1	d2
0.16	3.7e-13
0.47	7e-14
0.34	5.5e-14
0.34	5.4e-13
0.51	2e-13

y1	y2
0.16	3.5e-13
0.47	1.1e-13
0.34	8.2e-14
0.36	4.8e-13
0.51	1.9e-13

After 1726 epochs

train percent: 90%, MSE: 0.0037%

val percent: 10%, MSE: 0.0019%

Trial No.: 2 Train method: qn

First 5 val. samples of d & y

d1	d2
0.15	2.6e-12
0.47	7e-14
0.27	1e-13
0.35	2.5e-14
0.24	2.6e-13

y1	y2
0.15	2.2e-12
0.46	1.1e-13
0.27	1.1e-13
0.34	6.7e-14

0.23 2.3e-13  
 After 2376 epochs  
 train percent: 90%, MSE: 0.0059%  
 val percent: 10%, MSE: 0.0038%

Trial No.: 2 Train method: gd  
 First 5 val. samples of d & y

d1	d2
0.15	2.6e-12
0.47	7e-14
0.27	1e-13
0.35	2.5e-14
0.24	2.6e-13

y1	y2
0.15	2.3e-12
0.46	1.2e-13
0.26	1.2e-13
0.34	5.4e-14
0.22	2.7e-13

After 1457 epochs  
 train percent: 90%, MSE: 0.0070%  
 val percent: 10%, MSE: 0.0049%

Trial No.: 3 Train method: qn  
 First 5 val. samples of d & y

d1	d2
0.23	6.8e-14
0.24	2.2e-13
0.4	7.5e-14
0.28	8.1e-14
0.13	4.4e-13

y1	y2
0.22	8.6e-14
0.23	2e-13
0.4	1.1e-13
0.28	1e-13
0.15	4.3e-13

After 2412 epochs  
 train percent: 90%, MSE: 0.0056%  
 val percent: 10%, MSE: 0.0046%

Trial No.: 3 Train method: gd  
 First 5 val. samples of d & y

d1	d2
0.23	6.8e-14
0.24	2.2e-13
0.4	7.5e-14
0.28	8.1e-14
0.13	4.4e-13

```
      y1      y2
0.23 6.8e-14
0.23 2.4e-13
0.41 1.1e-13
0.27 7.8e-14
0.15 4.8e-13
After 2308 epochs
train percent: 90%, MSE: 0.0044%
val   percent: 10%, MSE: 0.0038%
```

```
Trial No.: 4   Train method: qn
First 5 val. samples of d & y
      d1      d2
0.31 2.5e-13
0.29 9.5e-13
0.24 1.6e-13
0.54 6.6e-14
0.21 6.8e-13
```

```
      y1      y2
0.32 2.1e-13
0.28 9.7e-13
0.23 1.7e-13
0.5  1.1e-13
0.2  5.6e-13
After 2168 epochs
train percent: 90%, MSE: 0.0065%
val   percent: 10%, MSE: 0.0104%
```

```
Trial No.: 4   Train method: gd
First 5 val. samples of d & y
      d1      d2
0.31 2.5e-13
0.29 9.5e-13
0.24 1.6e-13
0.54 6.6e-14
0.21 6.8e-13
```

```
      y1      y2
0.3  1.8e-13
0.28 9.6e-13
0.22 1.5e-13
0.51 1.2e-13
0.2  5.1e-13
After 1589 epochs
train percent: 90%, MSE: 0.0070%
val   percent: 10%, MSE: 0.0129%
```

```
Trial No.: 5   Train method: qn
First 5 val. samples of d & y
```

```

d1      d2
0.25  1.8e-12
0.34  3.6e-14
0.31  2.5e-13
0.24  2.2e-13
0.16  2.6e-13

```

```

y1      y2
0.24  1.9e-12
0.34   8e-14
0.32  2.1e-13
0.23  2.1e-13
0.16  2.6e-13

```

After 2317 epochs  
train percent: 90%, MSE: 0.0051%  
val percent: 10%, MSE: 0.0041%

Trial No.: 5 Train method: gd  
First 5 val. samples of d & y

```

d1      d2
0.25  1.8e-12
0.34  3.6e-14
0.31  2.5e-13
0.24  2.2e-13
0.16  2.6e-13

```

```

y1      y2
0.23  1.7e-12
0.34  7.6e-14
0.31  2.3e-13
0.23  2.2e-13
0.16  2.6e-13

```

After 1807 epochs  
train percent: 90%, MSE: 0.0033%  
val percent: 10%, MSE: 0.0035%

Trial No.: 6 Train method: qn  
First 5 val. samples of d & y

```

d1      d2
0.32  1.2e-13
0.16  3.7e-13
0.27  1.6e-13
0.4    6e-14
0.37  2.9e-13

```

```

y1      y2
0.33  1.2e-13
0.16  3.3e-13
0.27  1.6e-13
0.4    8.9e-14
0.38  2.7e-13

```

After 4246 epochs

train percent: 90%, MSE: 0.0047%  
 val percent: 10%, MSE: 0.0049%

Trial No.: 6 Train method: gd

First 5 val. samples of d & y

d1	d2
0.32	1.2e-13
0.16	3.7e-13
0.27	1.6e-13
0.4	6e-14
0.37	2.9e-13

y1	y2
0.32	1.3e-13
0.16	3.1e-13
0.26	1.7e-13
0.4	9.3e-14
0.38	2.7e-13

After 2885 epochs

train percent: 90%, MSE: 0.0043%  
 val percent: 10%, MSE: 0.0045%

Trial No.: 7 Train method: qn

First 5 val. samples of d & y

d1	d2
0.35	2.5e-14
0.27	1.2e-13
0.47	5.8e-14
0.24	1.6e-13
0.18	2.9e-13

y1	y2
0.35	6.7e-14
0.27	1.2e-13
0.47	1e-13
0.23	1.5e-13
0.18	3.1e-13

After 2372 epochs

train percent: 90%, MSE: 0.0051%  
 val percent: 10%, MSE: 0.0030%

Trial No.: 7 Train method: gd

First 5 val. samples of d & y

d1	d2
0.35	2.5e-14
0.27	1.2e-13
0.47	5.8e-14
0.24	1.6e-13
0.18	2.9e-13

y1	y2
----	----

0.35 4.9e-14  
 0.27 1.2e-13  
 0.47 9.3e-14  
 0.24 1.4e-13  
 0.18 2.7e-13  
 After 1921 epochs  
 train percent: 90%, MSE: 0.0052%  
 val percent: 10%, MSE: 0.0037%

Trial No.: 8 Train method: qn  
 First 5 val. samples of d & y

d1	d2
0.44	2.2e-13
0.23	1.1e-13
0.24	2e-13
0.11	2e-13
0.32	1.2e-13

y1	y2
0.45	2e-13
0.22	1.1e-13
0.23	1.8e-13
0.12	1.8e-13
0.32	1.2e-13

After 4904 epochs  
 train percent: 90%, MSE: 0.0020%  
 val percent: 10%, MSE: 0.0020%

Trial No.: 8 Train method: gd  
 First 5 val. samples of d & y

d1	d2
0.44	2.2e-13
0.23	1.1e-13
0.24	2e-13
0.11	2e-13
0.32	1.2e-13

y1	y2
0.46	2.1e-13
0.23	1.2e-13
0.24	1.9e-13
0.13	1.9e-13
0.33	1.3e-13

After 2097 epochs  
 train percent: 90%, MSE: 0.0072%  
 val percent: 10%, MSE: 0.0061%

Trial No.: 9 Train method: qn  
 First 5 val. samples of d & y

d1	d2
0.34	8.2e-14

0.29 5.1e-14  
 0.47 7e-14  
 0.17 2.8e-13  
 0.19 1.3e-12

y1 y2  
 0.33 1e-13  
 0.28 7.5e-14  
 0.46 1.1e-13  
 0.17 2.4e-13  
 0.18 1.4e-12

After 3292 epochs  
 train percent: 90%, MSE: 0.0044%  
 val percent: 10%, MSE: 0.0035%

Trial No.: 9 Train method: gd  
 First 5 val. samples of d & y

d1 d2  
 0.34 8.2e-14  
 0.29 5.1e-14  
 0.47 7e-14  
 0.17 2.8e-13  
 0.19 1.3e-12

y1 y2  
 0.33 9.5e-14  
 0.29 7.1e-14  
 0.47 9.2e-14  
 0.16 2.8e-13  
 0.18 1.4e-12

After 8205 epochs  
 train percent: 90%, MSE: 0.0011%  
 val percent: 10%, MSE: 0.0014%

Trial No.: 10 Train method: qn  
 First 5 val. samples of d & y

d1 d2  
 0.1 1.8e-12  
 0.2 3.3e-13  
 0.18 3.3e-13  
 0.48 3.5e-14  
 0.17 1.6e-13

y1 y2  
 0.13 1.9e-12  
 0.2 3.1e-13  
 0.18 3.4e-13  
 0.47 7.1e-14  
 0.17 1.4e-13

After 2021 epochs  
 train percent: 90%, MSE: 0.0059%  
 val percent: 10%, MSE: 0.0049%



Trial No.: 10 Train method: gd

First 5 val. samples of d & y

```
  d1      d2
  0.1  1.8e-12
  0.2  3.3e-13
  0.18 3.3e-13
  0.48 3.5e-14
  0.17 1.6e-13
```

```
  y1      y2
  0.13 1.9e-12
  0.19 3.2e-13
  0.18 3.3e-13
  0.47 5.8e-14
  0.17 1.4e-13
```

After 1377 epochs

train percent: 90%, MSE: 0.0058%

val percent: 10%, MSE: 0.0042%

error train QN: 0.005100%error val QN: 0.004492%error train GD:  
0.004902%error val GD: 0.004695%

## new functions

```
function [u_new, v_new] = update_gd(u, v, x, d, alpha,  
    act_type,act_out,batch_size)  
%UPDATE_GD Update Weights with Gradient Descendent  
% update_gd(u, v, x, d, alpha, act_type,act_out) updates weights with  
GD  
% Inputs:  
% u: weight of the input layer  
% v: weight of the hidden layers  
% x: input matrix  
% d: actual output matrix  
% alpha: negative learning rate  
% act_type: type of activation function: 'sigmoid', 'tanh' or 'relu'  
% act_out: option of activation function on the output layer  
% train_method: gradient descendent: 'gd', quasi-Newton: 'qn'  
% batch_size: batch size of data while training  
% Outputs:  
% u_new: weight of the input layer after a poch  
% v_new: weight of the hidden layers after a epoch  
len = ceil(length(d) / batch_size);  
for ii = 1:len  
    start = (ii-1) * batch_size+1;  
    if ii == len  
        [x_ss, d_ss] = deal(x(start:end, :), d(start:end, :));  
    else  
        [x_ss, d_ss] = deal(x(start:start+batch_size-1, :), ...  
            d(start:start+batch_size-1, :));
```

```

end
[x_ss, d_ss] = deal(x(ii, :), d(ii, :));
[y_ss, ~, active_z] = calc_ann(x_ss, u, v, act_type, act_out);
grad_u = get_der_u(v, active_z, x_ss, y_ss, d_ss, act_type, act_out);
grad_v = get_der_v(v, active_z, y_ss, d_ss, act_type, act_out);
u = u + alpha * grad_u;
v = add(v, multiply(alpha, grad_v));
end
u_new = u; v_new = v;
end

function [u_new, v_new] = update_qn(u, v, x, d, alpha,
    act_type, act_out, batch_size)
%UPDATE_GD Update Weights with Gradient Descendent
% update_gd(u, v, x, d, alpha, act_type, act_out) updates weights with
GD
% Inputs:
% u: weight of the input layer
% v: weight of the hidden layers
% x: input matrix
% d: actual output matrix
% alpha: negative learning rate
% act_type: type of activation function: 'sigmoid', 'tanh' or 'relu'
% act_out: option of activation function on the output layer
% train_method: gradient descendent: 'gd', quasi-Newton: 'qn'
% batch_size: batch size of data while training
% Outputs:
% u_new: weight of the input layer after a poch
% v_new: weight of the hidden layers after a epoch
s = []; y = []; rho = []; n_corrs = 10; % default memory for s, y = 10
function output = calc_ann_simple(x, u, v, act_type, act_out)
[output, ~, ~] = calc_ann(x, u, v, act_type, act_out);
end
len = ceil(length(d) / batch_size);
for ii = 1:len
    start = (ii-1) * batch_size+1;
    if ii == len
        [x_ss, d_ss] = deal(x(start:end, :), d(start:end, :));
    else
        [x_ss, d_ss] = deal(x(start:start+batch_size-1, :), ...
            d(start:start+batch_size-1, :));
    end
    [y_ss, ~, active_z] = calc_ann(x_ss, u, v, act_type, act_out);
    grad_u = get_der_u(v, active_z, x_ss, y_ss, d_ss, act_type, act_out);
    grad_v = get_der_v(v, active_z, y_ss, d_ss, act_type, act_out);
    func = @(u,
v)calc_mse(calc_ann_simple(x_ss, u, v, act_type, act_out), d_ss);
    [weight, node_input, node_output, layer] = combine_weights(u, v);
    [grad_weight, ~, ~, ~] = combine_weights(grad_u, grad_v);
    if size(s, 2) == n_corrs
        s(:, 1) = []; y(:, 1) = []; rho(1) = [];
    end
    if ii == 1

```

```
s = weight;
y = grad_weight;
rho = 1 / (weight'* grad_weight);
else
    s = [s weight - weight_prev];
    y = [y grad_weight - grad_weight_prev];
    rho = [rho 1 / (s(:, end)'* y(:, end))];
end
weight_prev = weight;
grad_weight_prev = grad_weight;
direction = search_direction(s, y, rho, grad_weight);
product = grad_weight'* direction;% product: gradient, search
direction
[du, dv] = separate_weights(direction,node_input, node_output,
layer);
alpha_adapt = line_search(func, u, v, du, dv, -alpha, product);
alpha_ada = - alpha_adapt;
u = u + alpha_ada * grad_u;
v = add(v, multiply(alpha_ada, grad_v));
end
u_new = u; v_new = v;
end

function [weight, node_input, node_output, layer] = combine_weights(u,
v)
%COMBINE WEIGHTS Combine Weights to a Vector
% combine_weights(u, v) combines u and v to a vector: weight
% Inputs:
% u: weight of the input layer
% v: weight of the hidden layers
% Outputs:
% weight: combined vector of weights, shape=(:, 1)
% node_input: dimension of input
% node_output: dimension of output
% layer: number of nodes for hidden layers
node_input = size(u, 2)-1;
node_output = size(v{end}, 1);
layer = zeros(1, length(v));
for ii = 1:length(v)
    layer(ii) = size(v{ii}, 2) - 1;
end
len = sum( ([node_input layer]+1).*[layer node_output] );
weight = zeros(len, 1);
len_chunk = (node_input+1)*layer(1);
weight(1: len_chunk) = u(:);
start = len_chunk+1;
for ii = 1:length(layer)-1
    len_chunk = (layer(ii)+1)*layer(ii+1);
    weight(start: start+len_chunk-1) = v{ii}(:);
    start = start + len_chunk;
end
weight(start:end) = v{end}(:);
end
```

```

function [u, v] = separate_weights(weight, node_input, node_output,
    layer)
%SEPARATE WEIGHTS Separate Weight Vector to u, v
% combine_weights(u, v) separates weight vector to u, v
% Inputs:
%   weight: combined vector of weights, shape=(:, 1)
%   node_input: dimension of input
%   node_output: dimension of output
%   layer: number of nodes for hidden layers
% Outputs:
%   u: weight of the input layer
%   v: weight of the hidden layers
assert(sum([node_input layer]+1).*[layer
    node_output])==length(weight),...
    'node_input, node_output, layer not match length of weight');
u = zeros(layer(1), node_input+1);
v = cell(1, length(layer));
len_chunk = (node_input+1)*layer(1);
u = reshape(weight(1: len_chunk), size(u));
start = len_chunk+1;
for ii = 1:length(layer)-1
    len_chunk = (layer(ii)+1)*layer(ii+1);
    v{ii} = reshape(weight(start: start+len_chunk-1), ...
        [layer(ii+1), layer(ii)+1]);
    start = start + len_chunk;
end
v{end} = reshape(weight(start: end), ...
    [node_output, layer(end)+1]);
end

```

## functions used in Quasi-Newton method

```

function d = search_direction(s, y, rho, grad_weight)
% SEARCH DIRECTION Search Direction of Quasi-Newton: limit BFGS
% search_direction(s, y) find the search direction with history:
%   s_k, y_k
% reference: SCG algorithm
% 1. https://github.com/scipy/scipy/blob/master/scipy/optimize/
% lbfgsb.py
% 2. https://courses.engr.illinois.edu/ece544na/fa2014/nocedal80.pdf
% Input:
%   s: s(:, k) = s_k = weight_{k+1}-weight_k, shape=(:, n_corrs)
%   y: y(:, k) = y_k = gradient_{k+1}-gradient_k, shape=(:, n_corrs)
%   rho: rho(k) = rho_k = 1 / (s_k'*y_k), shape=(1, n_corrs)
%   grad_weight: gradient at weight_k, shape=(:, 1)
% Output:
%   d: search deirection -Hessian^{-1} * gradient
if isempty(s)
    d = - grad_weight;
    return
end
assert(all(size(s)==size(y)), 'size of s, y not equal');

```

```
n_corrs = size(s, 2);
alpha = zeros(1, n_corrs);
q = grad_weight;
for ii = n_corrs:-1:1
    alpha(ii) = rho(ii) * (s(:,ii))' * q;
    q = q - alpha(ii) * y(:,ii);
end
r = q;
for ii = 1:n_corrs
    beta = rho(ii) * (y(:,ii))' * r;
    r = r + s(:,ii) * (alpha(ii) - beta);
end
d = -r; % r = Hessian^{-1} * gradient
end

function alpha = line_search(func, u, v, du, dv, alpha_0, product, r,
    c)
% LINE SEARCH Line Search with Backtracking Method
% line_search(func, u, v, du, dv, r, c) backtracking line search
% reference: https://sites.math.washington.edu/~burke/crs/408/lectures/L7-line-search.pdf
% Input:
%   func: function
%   u: current u
%   v: current v
%   du: the search direction for u
%   dv: the search direction for v
%   alpha_0: initial step length (>=0)
%   r: backtrack step between (0,1) usually 1/2
%   c: (0,1) usually 10^{-4}
% Output:
%   alpha: adaptive step length (>=0)
if nargin < 8
    r = 1 / 2;
    c = 1e-4;
end
y = func(u, v);
alpha = alpha_0;
u_new = u + alpha * du;
v_new = add(v, multiply(alpha, dv));
y_new = func(u_new, v_new);
while y_new > y + c * alpha * product % Armijo condition
    alpha = r * alpha;
    u_new = u + alpha * du;
    v_new = add(v, multiply(alpha, dv));
    y_new = func(u_new, v_new);
end
end
```

## helper functions: operators of cell array

```
function list_sum = add(list_cell1, list_cell2)
```

```
%Add Cell Arrays: v = v1 + v2
assert(length(list_cell1)==length(list_cell2),'cell size not equal')
list_sum = cell(size(list_cell1));
for ii = 1:length(list_cell1)
    list_sum{ii} = list_cell1{ii} + list_cell2{ii};
end
end

function list_multiply = multiply(scalar, list_cell)
%Multiply Cell Array with a Scalar: v = k * v1
list_multiply = cell(size(list_cell));
for ii = 1:length(list_cell)
    list_multiply{ii} = scalar * list_cell{ii};
end
end
```

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