$$G(s) = rac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2} \ = rac{\omega_n^2}{(s + \zeta\omega_n + j\sqrt{1 - \zeta^2}\omega_n)(s + \zeta\omega_n - j\sqrt{1 - \zeta^2}\omega_n)} \ = rac{A}{s + \zeta\omega_n + j\sqrt{1 - \zeta^2}\omega_n} - rac{A}{s + \zeta\omega_n - j\sqrt{1 - \zeta^2}\omega_n}$$

Where  $-2Aj\sqrt{1-\zeta^2}\omega_n=\omega_n^2\Leftrightarrow A=rac{j\omega_n}{2\sqrt{1-\zeta^2}}.$  So

$$G(s) = rac{j\omega_n}{2\sqrt{1-\zeta^2}} \Bigg[ rac{1}{s+\zeta\omega_n+j\sqrt{1-\zeta^2}\omega_n} - rac{1}{s+\zeta\omega_n-j\sqrt{1-\zeta^2}\omega_n} \Bigg] \ g(t) = rac{j\omega_n}{2\sqrt{1-\zeta^2}} ig[ e^{-(\zeta\omega_n+j\sqrt{1-\zeta^2}\omega_n)t} - e^{-(\zeta\omega_n-j\sqrt{1-\zeta^2}\omega_n)t} ig] \ = rac{j\omega_n}{2\sqrt{1-\zeta^2}} e^{-\zeta\omega_n t} ig[ -2j\sin(\sqrt{1-\zeta^2}\omega_n t) ig] \ = rac{\omega_n}{\sqrt{1-\zeta^2}} e^{-\zeta\omega_n t} \sin(\sqrt{1-\zeta^2}\omega_n t)$$

So, the output y(t) with  $y(0_{-})=0$  would be

$$Y(s) = rac{1}{s}G(s) \Leftrightarrow y(t) = u(t) * g(t) = \int_{0_{-}}^{t}g( au)d au \ \mathbb{L}[y'(t)] = sY(s) - y(0_{-}) = sY(s) = G(s) \ y'(t) = g(t) = rac{\omega_n}{\sqrt{1-\zeta^2}}e^{-\zeta\omega_n t}\sin(\sqrt{1-\zeta^2}\omega_n t)$$

Consider such an integral, where  $an(\phi)=rac{b}{a}$ 

$$\int_{0}^{t} e^{-a\tau} \sin(b\tau) d\tau = \int_{0}^{t} \operatorname{Im} \left[ e^{(-a+jb)\tau} \right] d\tau = \operatorname{Im} \left[ \int_{0}^{t} e^{(-a+jb)\tau} d\tau \right]$$

$$= \operatorname{Im} \left[ \frac{a+jb}{a^{2}+b^{2}} [1 - e^{-at} \cos(bt) - je^{-at} \sin(bt)] \right]$$

$$= \frac{1}{a^{2}+b^{2}} [-ae^{-at} \sin(bt) + b - be^{-at} \cos(bt)]$$

$$= \frac{b}{a^{2}+b^{2}} - \frac{e^{-at}}{a^{2}+b^{2}} \sqrt{a^{2}+b^{2}} \sin(bt+\phi)$$

substitute  $a,b \leftarrow \zeta \omega_n, \sqrt{1-\zeta^2}\omega_n$  , we can derive the expression for y(t)

$$egin{aligned} y(t) &= \int_{0_{-}}^{t} g( au) d au = rac{\omega_n}{\sqrt{1-\zeta^2}} \int_{0_{-}}^{t} e^{-\zeta\omega_n au} \sin(\sqrt{1-\zeta^2}\omega_n au) d au \ &= rac{\omega_n}{\sqrt{1-\zeta^2}} iggl[ rac{\sqrt{1-\zeta^2}\omega_n}{\omega_n^2} - rac{e^{-\zeta\omega_n t}}{\omega_n} \sin(\sqrt{1-\zeta^2}\omega_n t + \phi) iggr] \ &= 1 - rac{e^{-\zeta\omega_n t}}{\sqrt{1-\zeta^2}} \sin(\sqrt{1-\zeta^2}\omega_n t + \phi) \end{aligned}$$

where 
$$\tan(\phi) = \frac{b}{a} = \frac{\sqrt{1-\zeta^2}}{\zeta}, \sin(\phi) = \sqrt{1-\zeta^2}, \cos(\phi) = \zeta$$

## Calculate $T_s$

$$T_s = rac{4}{\zeta \omega_n} \Leftrightarrow e^{-\zeta \omega_n T_s} = e^{-4} pprox 0.02$$

## Calculate overshoot % and $T_p$

by let  $y'(t)ert_{t=T_p}=0$ 

$$egin{aligned} y'(t)|_{t=T_p} &= rac{\omega_n}{\sqrt{1-\zeta^2}} e^{-\zeta\omega_n T_p} \sin(\sqrt{1-\zeta^2}\omega_n T_p) = 0 \ \sqrt{1-\zeta^2}\omega_n T_p &= \pi \Leftrightarrow T_p &= rac{\pi}{\sqrt{1-\zeta^2}\omega_n} \end{aligned}$$

consider the overshoot % at  $t=T_p$ 

$$egin{align} 1+\% &\equiv y(t)|_{t=T_p} = 1 - rac{e^{-\zeta\omega_n T_p}}{\sqrt{1-\zeta^2}} ext{sin}(\sqrt{1-\zeta^2}\omega_n T_p + \phi) \ &= 1 - rac{e^{-\zeta\omega_n T_p}}{\sqrt{1-\zeta^2}} ext{sin}(\pi+\phi) = 1 + rac{e^{-\zeta\omega_n T_p}}{\sqrt{1-\zeta^2}} \sqrt{1-\zeta^2} \ &= 1 + e^{-\zeta\omega_n T_p} = 1 + e^{-\pi rac{\zeta}{\sqrt{1-\zeta^2}}} \end{aligned}$$

So, we find the relationship between the overshoot % and  $\zeta$ 

$$\% = e^{-\pirac{\zeta}{\sqrt{1-\zeta^2}}} \Leftrightarrow -rac{\ln(\%)}{\pi} = rac{\zeta}{\sqrt{1-\zeta^2}} \ rac{-\ln(\%)}{\sqrt{\pi^2+\ln^2(\%)}} = \zeta$$

## **Summary**

$$\zeta = rac{-\ln(\%)}{\sqrt{\ln(\%)^2 + \pi^2}} 
onumber \ T_s = rac{4}{\zeta\omega_n} 
onumber \ T_p = rac{\pi}{\sqrt{1-\zeta^2}\omega_n}$$

where  $T_s$  represents settling time,  $T_p$  represents peak time. consider  $s^2+2\zeta\omega_n s+\omega_n^2$ , we can determine the coefficients for s,1 by

$$egin{align} 2\zeta\omega_n &= rac{8}{T_s} = rac{-2\ln(\%)}{T_p} \ & \omega_n^2 &= rac{16(\ln(\%)^2 + \pi^2)}{\ln(\%)^2 T_s^2} = rac{\ln(\%)^2 + \pi^2}{T_p^2} \ \end{gathered}$$